

GLOBAL CHANGE OBSERVATION MISSION (GCOM)

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ABSTRACT

JAXA (Japan Aerospace Exploration Agency) initiated GCOM (Global Change Observation Mission) to monitor the global Earth surface and contribute to the research of the climate change and the operational usage. By using the satellite observation data in the climate system model, it is expected that the prediction accuracy of the climate change will be improved. This information will be useful for making a policy to mitigate and adapt to the climate change.

GCOM consists of 3 generations of satellites to make observation for more than 10 years. The satellites of the first generation, GCOM-W1 and GCOM-C1, have been developed to aim at the launch in Japanese Fiscal Year 2011 and 2014, respectively.

KEY WORDS: GCOM, GCOM-W, GCOM-C, AMSR2, SGLI, VNR, IRS

1. INTRODUCTION

Understanding, assessment, and prediction of global climate change are very important for human life recently. At the Third Earth Observation Summit held in Brussels in February 2005, the 10-year implementation plan for GEOSS (Global Earth Observation System of Systems) was adopted. The vision for GEOSS is to realize a future, when decisions and actions for the benefit of humankind are informed by coordinated, comprehensive, and sustained Earth observations and information. Space agencies are constructing space components, in order to satisfy this vision. In the nine societal benefit areas of GEOSS in space applications, Japan emphasizes monitoring of disaster, climate change, and water circulation.

As a contribution to this activity, JAXA (Japan Aerospace Exploration Agency) initiated GCOM (Global Change Observation Mission). GCOM will take over the mission of the Advanced Earth Observing Satellite-II (ADEOS-II) and be developed into a long-term mission for monitoring the Earth.

2. OVERVIEW OF GCOM

GCOM contains of 2 kinds of satellites, GCOM-W series satellites and GCOM-C series satellites. The W of GCOM-W stands for “water” and GCOM-W will contribute to the observation related to the global water and energy circulations, which installs AMSR2 (Advanced Microwave Radiometer 2). On the other hand the C of GCOM-C stands for “climate” and GCOM-C will contribute to the surface and atmospheric measurements related to the carbon cycle and radiation budget, which installs SGLI (Second Generation Global Imager).

GCOM is a long-term mission to require observation for more than 10 years. To realize this purpose it is planned that 3 generations of satellites of 5 year design life will be launched in series, taking

account of one year operational overlap in orbit for calibration. This plan enables over 13-year observation in total. [1]

Table 1. The characteristics of GCOM-W1 and GCOM-C1

| | GCOM-W1 | GCOM-C1 |
|------------------|---|--|
| Orbit | Sun synchronous orbit (A-Train orbit) Altitude : 699.6km (on Equator) Inclination : 98.2° Local sun time : 13:30±15min | Sun synchronous orbit Altitude : 798km (on Equator) Inclination : 98.6° Local sun time : 10:30±15 min |
| Life | 5 years | 5 years |
| Launch | JFY 2011 by H-IIA Rocket | JFY 2014 by H-IIA Rocket |
| Satellite scale | 5.1m (X) × 17.5m (Y) × 3.4m (Z) (on-orbit) | 4.6m (X) × 16.3m (Y) × 2.8m (Z) (on-orbit) |
| Satellite mass | 1991kg | 2093kg |
| Power generation | More than 3880W (EOL) | More than 4000W (EOL) |

3. GCOM-W1

3.1. Satellite system

GCOM-W1 is the first generation of GCOM-W series satellites. The characteristics of GCOM-W1 system are shown in Table 1. The attitude of GCOM-W1 is controlled by 4 reaction wheels in response to the signal from IRU (Inertial Reference Unit) calibrated by Star Trackers and GPS receivers. The electrical power system has 2 redundant systems including batteries and solar paddles, and therefore the satellite can survive even if one solar paddle has a failure. The satellite is controlled by the telecommands from the ground stations using S band link. The real-

time and stored observation data are transmitted to the ground stations by X band link, together with the real-time and stored telemetries.

The satellite has been developed since 2007. AMSR2 CDR was finished in January, 2009 and the flight model has been manufactured. The AMSR2 integration has been performed and the environmental test will be performed in summer, 2010. The satellite system CDR finished in December 2009. At the present the flight models of satellite bus components are under the electrical and environmental tests. The system test of the GCOM-W1 flight model will be performed from autumn, 2010. GCOM-W1 is planned to be launched in JFY (Japanese Fiscal Year) 2011. Figure 1 shows the configuration of GCOM-W1 in orbit. [2]

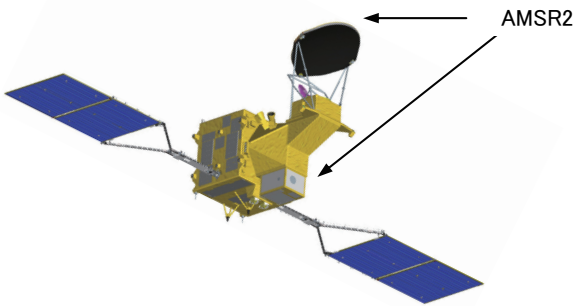


Figure 1. In-orbit configuration of GCOM-W1

3.2. AMSR2

AMSR2 is the follow-on instrument of AMSR-E installed on AQUA. The sensor unit including the main reflector is rotated at 40 rpm and receives the RF radiated from the Earth. The RF level from the Earth is calibrated by both the cold referenced data from the deep space reflected by the cold sky mirror and the hot referenced data from the hot temperature noise source of AMSR2. The configuration of AMSR2 sensor unit is shown in Figure 2.

AMSR2 has receivers of 6 channels, from 7 GHz to 89 GHz. These are basically same as AMSR-E, but 7.3 GHz channel was newly added to mitigate the RF interference of 6.9 GHz by the terrestrial communication link. The detailed channels and frequencies of AMSR2 are indicated in Table 2. The diameter of the main reflector becomes larger to about 2 m. The thermal control of the hot load has been improved and then its surface temperature will be much more stable than AMSR-E. The swath of AMSR2 is 1450 km in a cross track. [3]

The level 2 products of AMSR2 are listed in Table 3.

Table 2. The AMSR2 channels and frequencies

| AMSR2 Channel Set | | | | |
|--------------------|------------------|--------------|-------------------------------------|------------------------|
| Center Freq. [GHz] | Band width [MHz] | Polarization | Beam width [deg] (Ground res. [km]) | Sampling interval [km] |
| 6.925/7.3 | 350 | V and H | 1.8 (35 x 62) | 10 |
| | | | 1.7 (34 x 58) | |
| 10.65 | 100 | | 1.2 (24 x 42) | |
| 18.7 | 200 | | 0.65 (14 x 22) | |
| 23.8 | 400 | | 0.75 (15 x 26) | |
| 36.5 | 1000 | | 0.35 (7 x 12) | |
| 89.0 | 3000 | 0.15 (3 x 5) | 5 | |

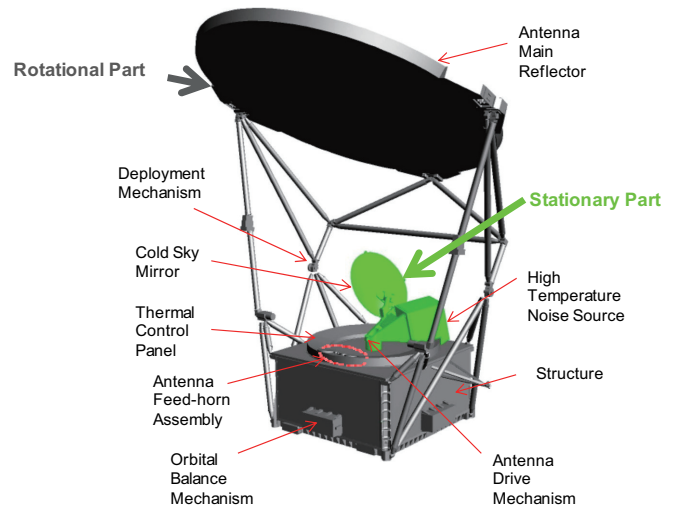


Figure 2. The overview of AMSR2 sensor unit

Table 3. The AMSR2 Level 2 Products

| GCOM-W Geophysical Products | Region | Resolution |
|-------------------------------|------------------------------|------------|
| Integrated Water Vapor | Global Ocean | 15km |
| Integrated Cloud Liquid Water | Global Ocean | 15km |
| Precipitation | Global except Cold Latitudes | 15km |
| Sea Surface Temperature | Global Ocean | 50km |
| Sea Surface Wind Speed | Global Ocean | 15km |
| Sea Ice Concentration | High-Latitude Ocean | 15km |
| Snow depth | Land | 30km |
| Soil Moisture Content | Land | 50km |

4. GCOM-C1

4.1. Satellite system

GCOM-C1 is also the first generation of GCOM-C series satellites, whose characteristics are shown in Table 1. The design of bus system is almost common between GCOM-W1 and GCOM-C1. The development started in 2009 and the designs of engineering models of SGLI and some bus components, and thermal/structural system model have been performed. The prototype of SGLI was manufactured and had been tested for 4 years. These components are refurbished and will be used in the engineering model test. GCOM-C1 is planned to be launch in JFY 2014. Figure 2 indicates the configuration of GCOM-C1 in orbit.

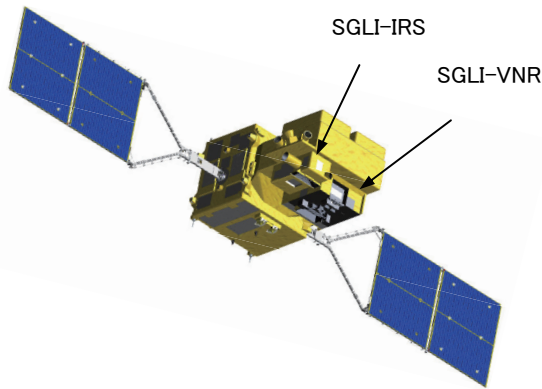


Figure 3. In-orbit configuration of GCOM-C1

4.2. SGLI

GCOM-C1 installs SGLI, which consists of VNR (Visible and Near-Infrared Radiometer) and IRS (Infrared Scanner). The VNR has 11 channels of non-polarized observation and 2 channels of polarized observation, from 380 nm to 870 nm wave length. The polarized channels observe in three polarization angles (0, 60 and 120 degrees) and can tilt forward and backward by 45 degrees in the along-track direction. The IRS has 4 shortwave infrared channels (from 1.05 to 2.21 micro meters wave length) and 2 thermal infrared channels (10.8 and 12 micro meters wave length). The detailed wavelength of each channel is shown in Table 4. The overview of VNR and IRS is illustrated in Figure 4 and 5. The swath of the VNR is 1150 km in a cross track and that of the IRS is 1400 km.

The level 2 products of SGLI are indicated in Table 5.

Table 4. The SGLI channels and wavelengths

| SGLI channels | | | | | |
|---------------|-----------|-----------------|--------------------------------------|-----------|------|
| CH | λ | $\Delta\lambda$ | L_{std} | L_{max} | IFOV |
| | nm | | VN, P: $W/m^2/sr/\mu m$ T: Kelvin | | m |
| VN1 | 380 | 10 | 60 | 210 | 250 |
| VN2 | 412 | 10 | 75 | 250 | 250 |
| VN3 | 443 | 10 | 64 | 400 | 250 |
| VN4 | 490 | 10 | 53 | 120 | 250 |
| VN5 | 530 | 20 | 41 | 350 | 250 |
| VN6 | 565 | 20 | 33 | 90 | 250 |
| VN7 | 673.5 | 20 | 23 | 62 | 250 |
| VN8 | 673.5 | 20 | 25 | 210 | 250 |
| VN9 | 763 | 12 | 40 | 350 | 1000 |
| VN10 | 868.5 | 20 | 8 | 30 | 250 |
| VN11 | 868.5 | 20 | 30 | 300 | 250 |
| SW1 | 1050 | 20 | 57 | 248 | 1000 |
| SW2 | 1380 | 20 | 8 | 103 | 1000 |
| SW3 | 1630 | 200 | 3 | 50 | 250 |
| SW4 | 2210 | 50 | 1.9 | 20 | 1000 |
| T1 | 10800 | 740 | 300 | 340 | 500 |
| T2 | 12000 | 740 | 300 | 340 | 500 |
| P1 | 673.5 | 20 | 25 | 250 | 1000 |
| P2 | 868.5 | 20 | 30 | 300 | 1000 |

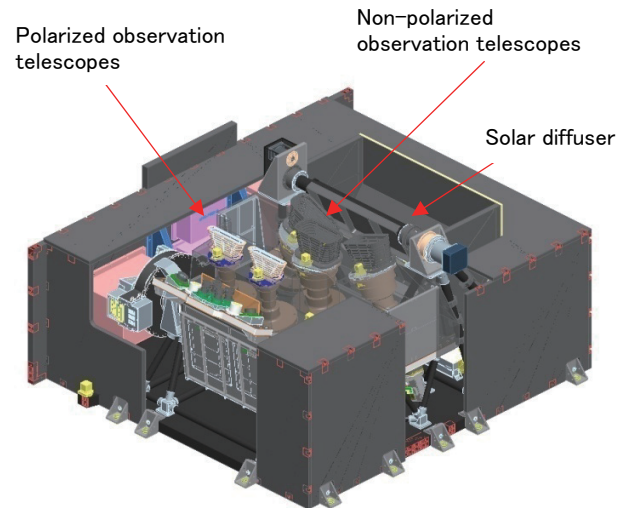


Figure 4. The overview of VNR

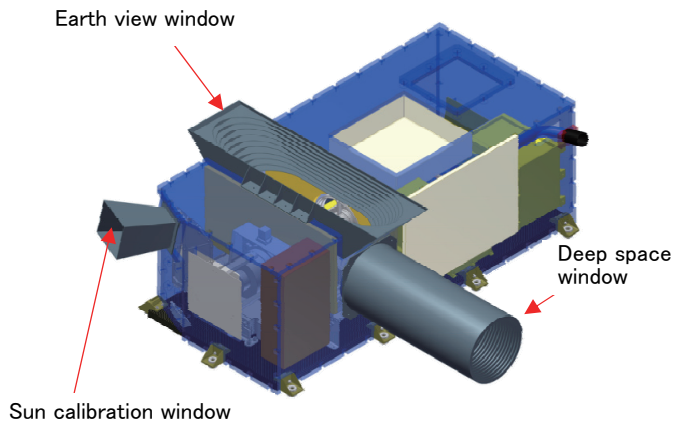


Figure 5. The overview of IRS

Table 5-1. The SGLI Level 2 Products

| GCOM-C Geophysical Products | | Resolution |
|---|--|-----------------------------|
| Land | Precise Geometrically Corrected Image | 250m |
| | Atmospherically Corrected Land Surface Reflectance | 250m |
| | Vegetation Index including NDVI and EVI | 250m |
| | Vegetation Roughness Index including BSI_P and BSI_V | 1km |
| | Shadow Index | 1km |
| | Land Surface Temperature | 500m |
| | Fraction of Absorbed Photosynthetically Active Radiation | 250m |
| | Leaf Area Index | 250m |
| | Above-Ground Biomass | 1km |
| | Land Net Primary Production | 1km |
| | Plant Water Stress trend Index | 500m |
| | Fire Detection Index | 500m |
| | Land Cover Type | 250m |
| | Land surface Albedo | 1km |
| Atmosphere | Cloud Flag including Cloud Classification and Phase | 1km |
| | Classified Cloud Fraction | |
| | Cloud Top Temperature and Height | |
| | Water Cloud Optical Thickness and Effective Radius | |
| | Ice Cloud Optical Thickness | |
| | Water Cloud Geometrical Thickness | Scene: 1km |
| | Aerosol over Ocean by Visible and Near Infrared | Global: 0.1deg |
| | Aerosol over Land by Near Ultra Violet | |
| | Aerosol over Land by Polarization | |
| | Long-Wave Radiation Flux | |
| Short-Wave Radiation Flux | | |
| Ocean | Normalized Water Leaving Radiance | |
| | Atmospheric Correction Parameters | |
| | Ocean Photosynthetically Available Radiation | |
| | Euphotic Zone Depth | Coast: 250m |
| | Chlorophyll-A Concentration | Open ocean: 1km |
| | Suspended Solid Concentration | Global: 4~9km |
| | Absorption Coefficient of Colored Dissolved Organic Matter | |
| | Inherent Optical Properties | |
| | Sea Surface Temperature | Coast: 500m Other: ditto |
| | Ocean Net Primary Production | Coast: 500m Other: ditto |
| Phytoplankton Function Type | Coast: 250m Other: ditto | |
| Red Tide | | |
| Multi Sensor Merged Ocean Color Parameters | Coast: 250m Open ocean: 1km | |
| Multi Sensor Merged Sea Surface Temperature | Coast: 500m Open ocean: 1km | |

Table 5-2. The SGLI Level 2 Products

| GCOM-C Geophysical Products | | Resolution |
|-----------------------------|---|-----------------------------|
| Cryosphere | Snow and Ice Covered Area | Scene: 250m Global: 1km |
| | Okhotsk Sea-Ice Distribution | 250m |
| | Snow and Ice Classification | 1km |
| | Snow Covered Area in Forest ad Mountain | 250m |
| | Snow and Ice Surface Temperature | Scene: 500m, Global: 1km |
| | Snow Grain Size of Shallow Layer | Scene: 250m, Global: 1km |
| | Snow Grain Size of Subsurface Layer | 1km |
| | Snow Grain Size of Top Layer | Scene: 250m, Global: 1km |
| | Snow and Ice Albedo | 1km |
| | Snow Impurity | Scene: 250m, Global: 1km |
| | Ice Sheet Surface Roughness | 1km |
| | Ice Sheet Boundary Monitoring | 250m |

5. DATA ACQUISITION AND DESTRIIBUTION

The global observation data stored in the data recorder inside the satellite will be received at Svalbard station in Norway once per orbit. Therefore the data latency of near real-time level 1 products will be achieved in 2.5 hours after the observation time in case of GCOM-W1. GCOM-W1 and GCOM-C1 have capability of direct readout that their real-time observation data can be down-linked to the ground stations. The real-time observation data over Japanese island will be transmitted to the domestic JAXA ground station.

The data product will be obtained at the GCOM website via internet, once researchers register themselves on the website. In order to develop the algorism of processing data to the level 2 products, JAXA issued the research announcements in 2008 and 2009 for GCOM-W1 and GCOM-C1 respectively. The 29 proposals for GCOM-W1 and 37 proposals for GCOM-C1 were accepted and developing activity has been performed. The PI workshop was held once a year and the progress was confirmed and evaluated.

6. INTERNATIONAL COOPERATION

GCOM-W1 will join the A-Train constellation led by NASA. The position of GCOM-W1 in the constellation is a few minutes prior to AQUA.

JAXA is discussing with NOAA to make cooperation in data exchange, calibration and validation, and data reception support. Both agencies and JPL have performed the feasibility study that the Dual-Frequency Scatterometer provided by NOAA/JPL will be installed on GCOM-W2, the next generation of GCOM-W1, together with AMSR3 which is follow-on instrument of AMSR2.

7. CONCLUSION

The development of GCOM-W1 and GCOM-C1 has been performed as planned. The flight model of GCOM-W1 is manufactured and integrated in order to be launched in JFY 2011. The study for GCOM-W2 is already started. GCOM has been going ahead steadily as a long term observation mission.

8. REHERENCES

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